

# Geol 600 Notable Historical Earthquakes

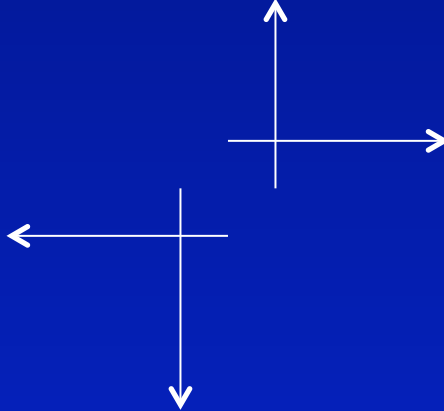
Source mechanisms and body wave  
radiation patterns

## Force Couples:

Forces must occur in opposing directions to conserve momentum

  $\leftarrow$  D  $\rightarrow$  no net torque

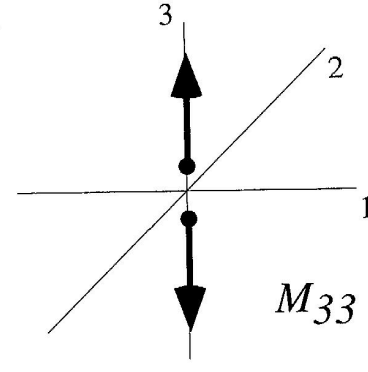
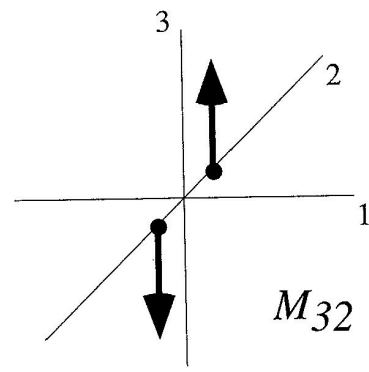
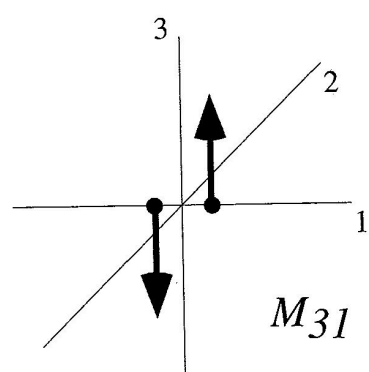
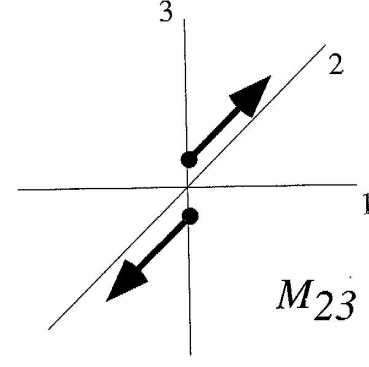
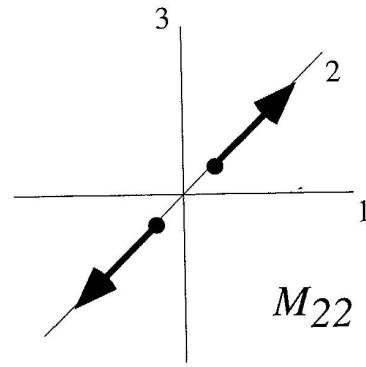
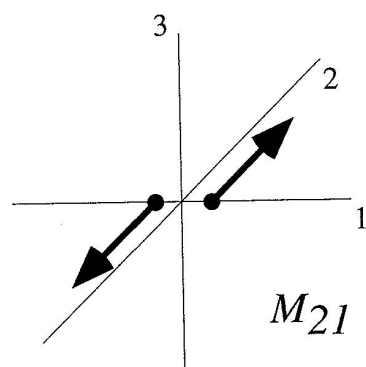
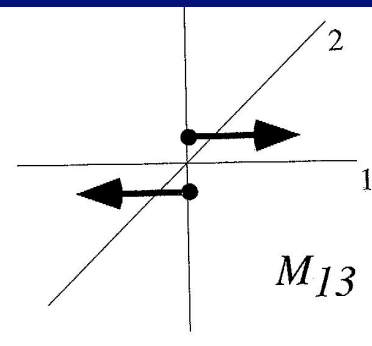
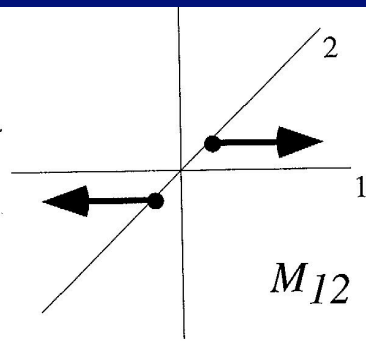
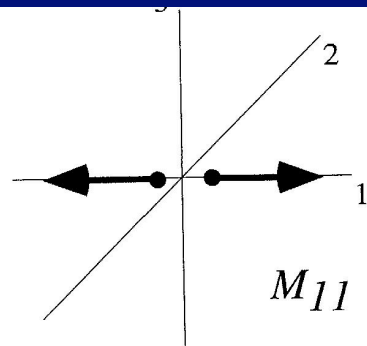
  $\leftarrow$  D  $\rightarrow$  net torque

  
double couple:  
no net torque

9 Force Couples  $M_{ij}$  (the moment tensor), 6 different ( $M_{ij}=M_{ji}$ ).  $|M|=fd$

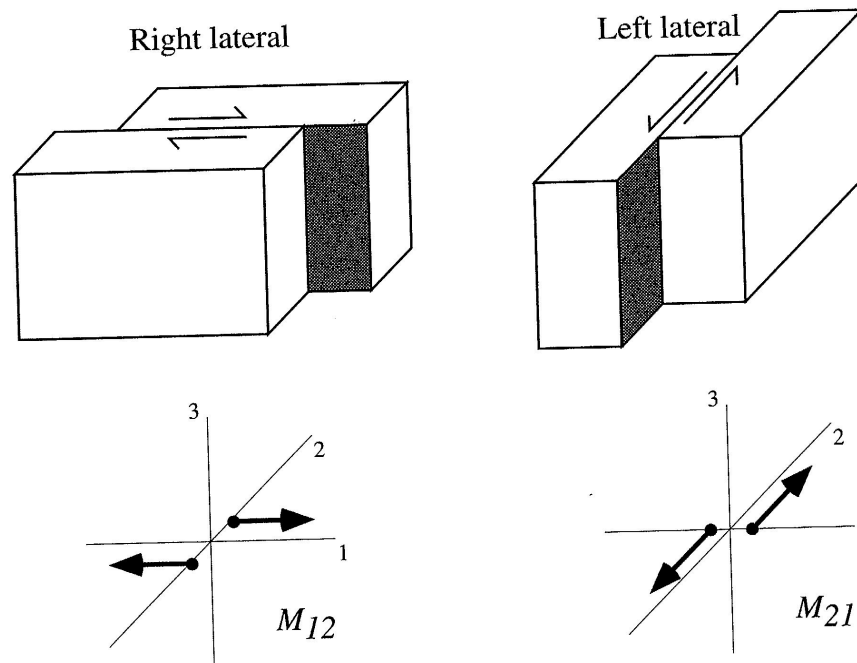
$$M = \begin{bmatrix} M_{11} & M_{12} & M_{13} \\ M_{21} & M_{22} & M_{23} \\ M_{31} & M_{32} & M_{33} \end{bmatrix}$$

Good approximation for distant earthquakes due to a point source  
Larger earthquakes can be modeled as a sum of point sources



Because of ambiguity  $M_{ij}=M_{ji}$  two fault planes are consistent with a double-couple model: the primary fault plane, and the auxillary fault plane (model for both generates same far-field displacements).

Distinguishing between the two requires further (geological) information



$$\mathbf{M} = \begin{bmatrix} 0 & M_0 & 0 \\ M_0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Example: vertical right-lateral along x

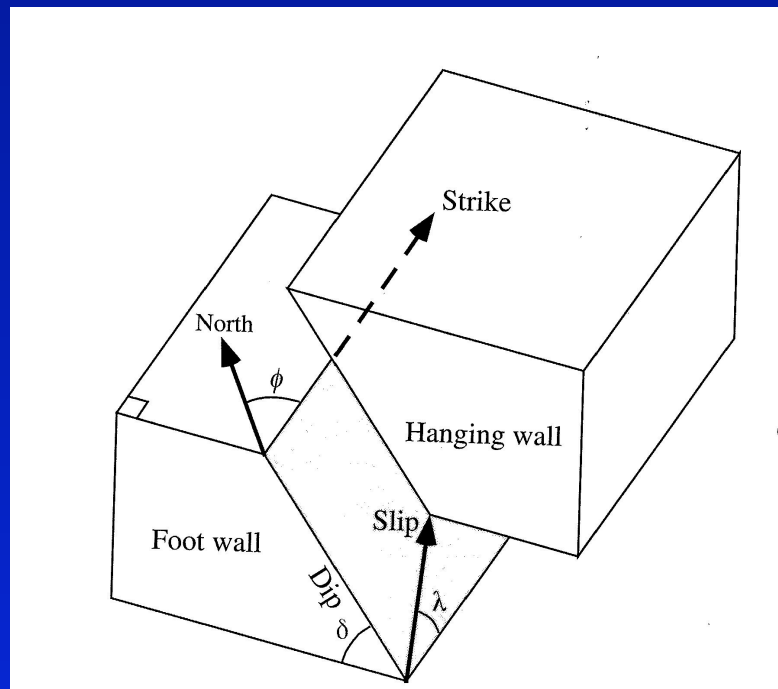
$M_0 = \mu DA$  scalar seismic moment (Nm)

Description of earthquakes using moment tensors:

Parameters: strike  $\phi$ , dip  $\delta$ , rake  $\lambda$

Right-lateral  $\lambda=180^\circ$ , left-lateral  $\lambda=0^\circ$ ,  $\lambda=90$  reverse,  $\lambda=-90$  normal faulting

Strike, dip, rake, slip define the focal mechanism



## Description of earthquakes using moment tensors:

$$M_{11} = -M_0(\sin\delta \cos\lambda \sin 2\phi_s + \sin 2\delta \sin\lambda \sin^2\phi_s),$$

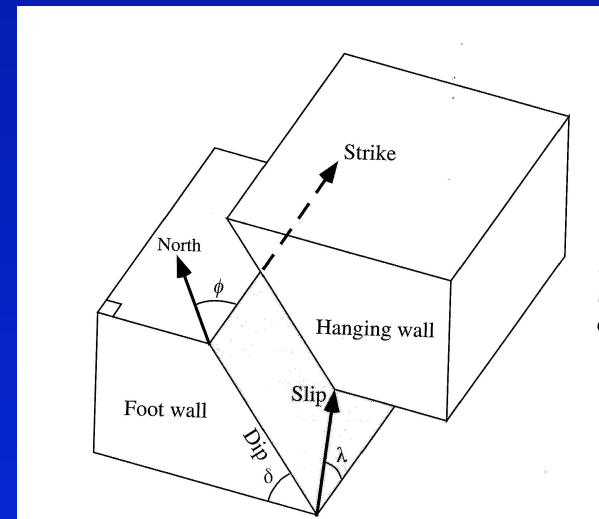
$$M_{12} = M_0(\sin\delta \cos\lambda \cos 2\phi_s + 0.5 \sin 2\delta \sin\lambda \sin 2\phi_s),$$

$$M_{13} = -M_0(\cos\delta \cos\lambda \cos\phi_s + \cos 2\delta \sin\lambda \sin\phi_s),$$

$$M_{22} = M_0(\sin\delta \cos\lambda \sin 2\phi_s - \sin 2\delta \sin\lambda \cos^2\phi_s),$$

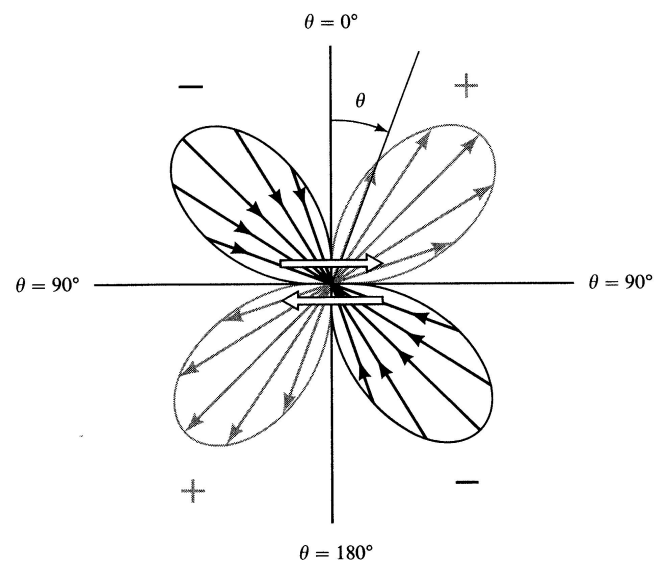
$$M_{23} = -M_0(\cos\delta \cos\lambda \sin\phi_s - \cos 2\delta \sin\lambda \cos\phi_s),$$

$$M_{33} = M_0 \sin 2\delta \sin\lambda.$$



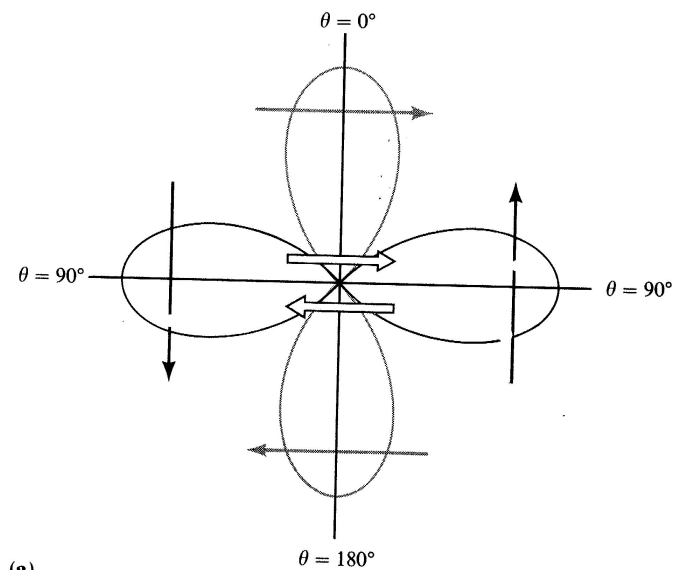


## P-waves



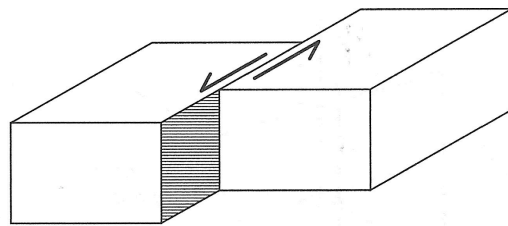
(a)

## S-waves

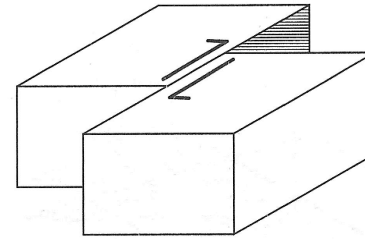


(a)

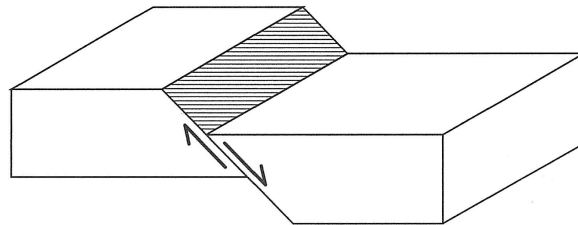
Determining an earthquake's mechanism from first P  
motions



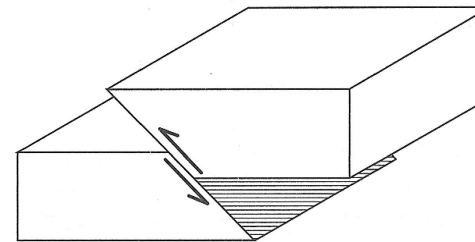
Left-lateral strike-slip fault  
( $\lambda = 0^\circ$ )



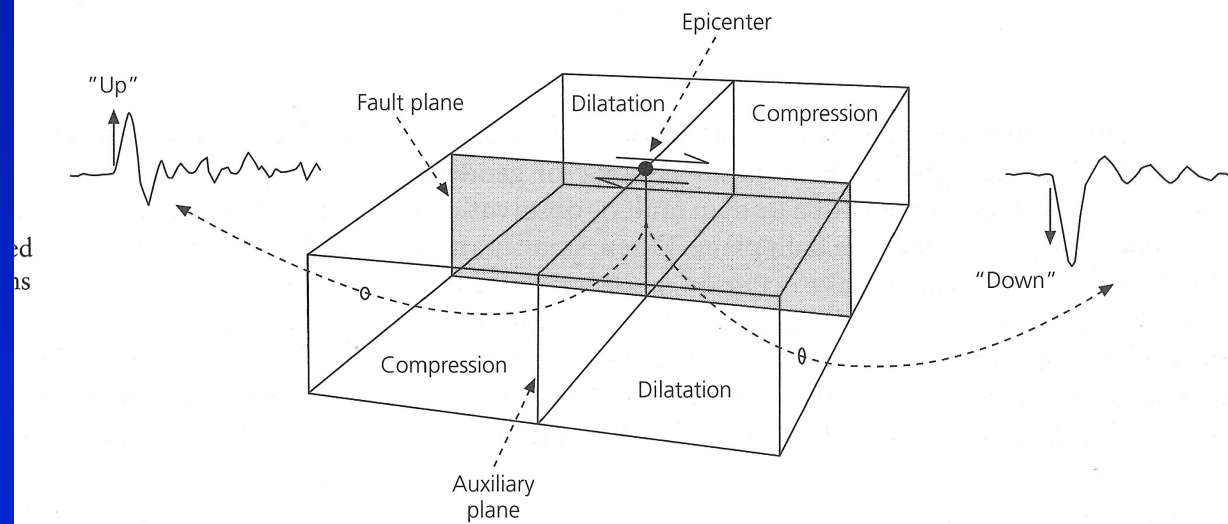
Right-lateral strike-slip fault  
( $\lambda = 180^\circ$ )



Normal dip-slip fault  
( $\lambda = -90^\circ$ )



Reverse dip-slip fault  
( $\lambda = 90^\circ$ )



# Take-off angle:

$$\frac{\sin i}{v} \frac{dT}{d\Delta} = 1$$

Table 4.2-1 P-wave take-off angles for a surface-focus earthquake.

Distance (°)	Take-off angle (°)	Distance (°)	Take-off angle (°)	Distance (°)	Take-off angle (°)
21	36	47	25	73	19
23	32	49	24	75	18
25	30	51	24	77	18
27	29	53	23	79	17
29	29	55	23	81	17
31	29	57	23	83	16
33	28	59	22	85	16
35	28	61	22	87	15
37	27	63	21	89	15
39	27	65	21	91	15
41	26	67	20	93	14
43	26	69	20	95	14
45	25	71	19	97	14

Source: After Pho and Bebe (1972).

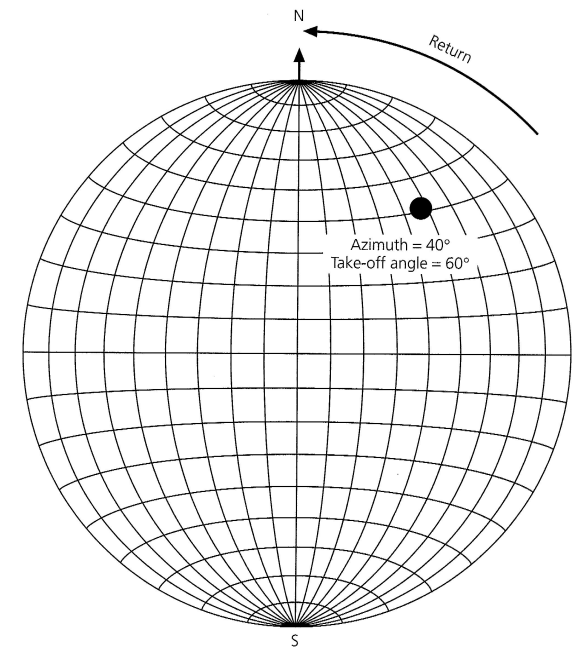
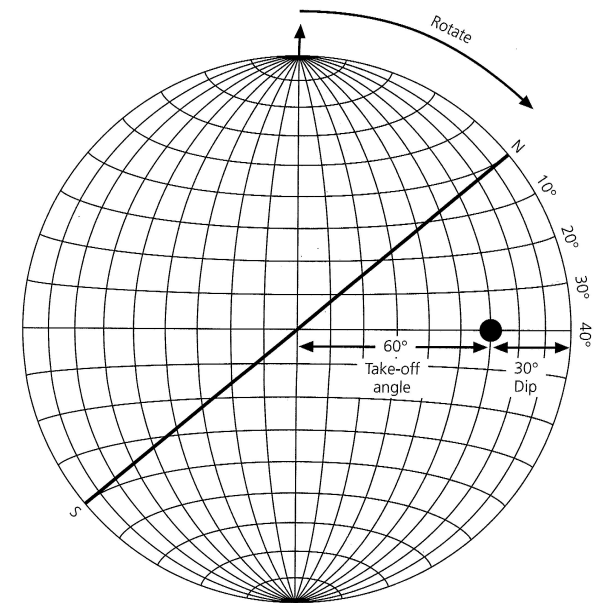
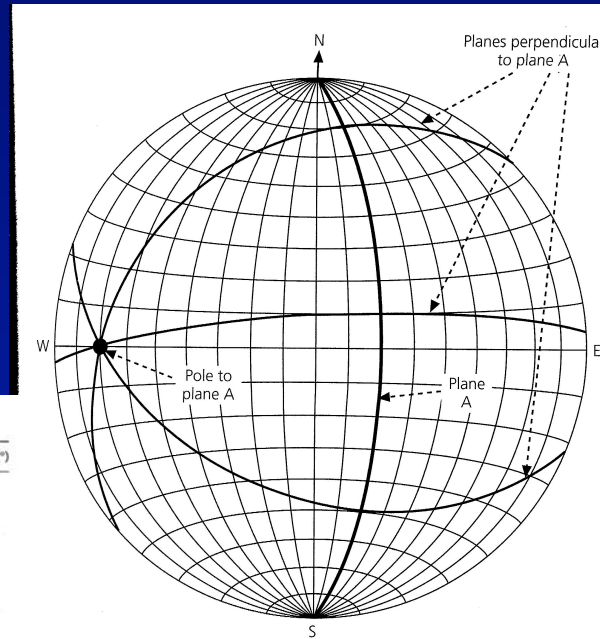
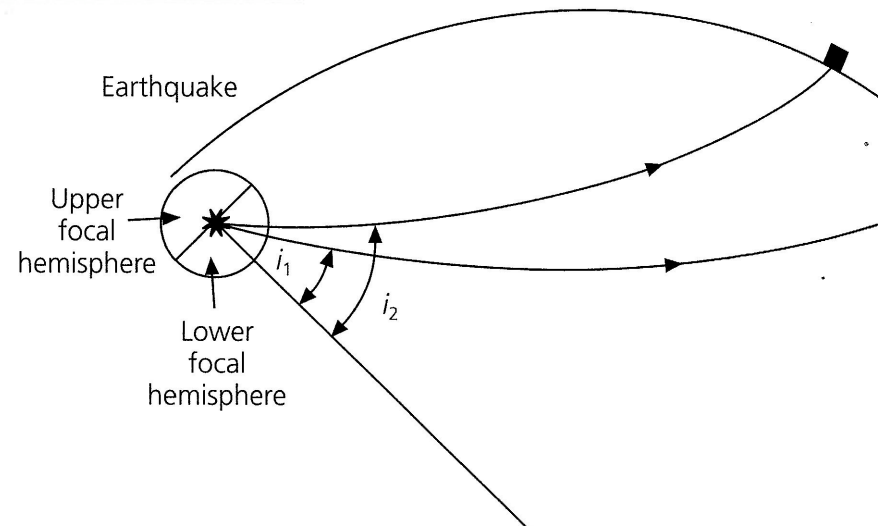
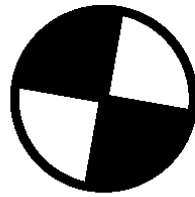
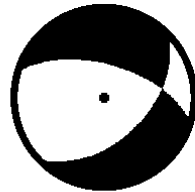


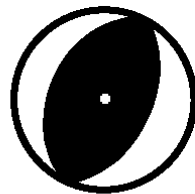
Fig. 4.2-8 The angle of incidence at the earthquake source is the a



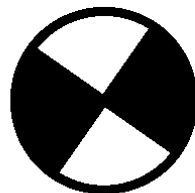
Type of faults:



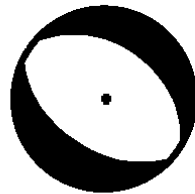
Type of faults:



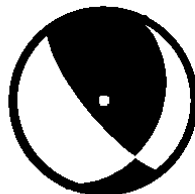
Type of faults:



Type of faults:



Type of faults:



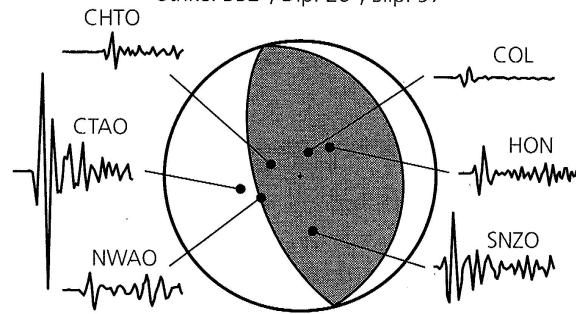
Type of faults:

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Thrust faulting, Vanuatu Islands, July 3, 1985

Location: 17.2°S, 167.8°E. Depth: 30 km

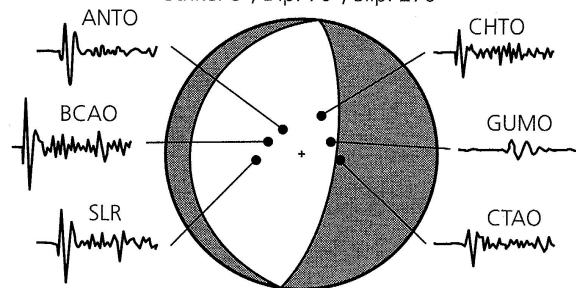
Strike: 352°, Dip: 26°, Slip: 97°



Normal faulting, mid-Indian rise, May 16, 1985

Location: 29.1°S, 77.7°E. Depth: 10 km

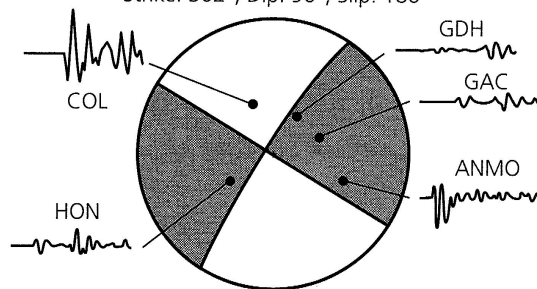
Strike: 8°, Dip: 70°, Slip: 270°



Strike-slip faulting, west of Oregon, March 13, 1985

Location: 43.5°N, 127.6°W. Depth: 10 km

Strike: 302°, Dip: 90°, Slip: 186°



0 120 240  
(s)

## Earthquake focal mechanism determination from first P motion (assuming double-couple model):

- Only vertical component instruments needed
- No amplitude calibration needed
- Initial P motion easily determined (up or down)
- Up: ray left the source in compressional quadrant
- Down: ray left source in dilatational quadrant
- Plotted on focal sphere (lower hemisphere)
- Allows division of focal sphere into compressional/dilatational quadrants
- Focal mechanism is then found from two orthogonal planes (projections on the focal sphere)

Earthquake focal mechanism determination from first P motion (assuming double-couple model):

- Focal sphere is shaded in compressional quadrants, generating 'beach ball'
- Normal faulting: white with black edges
- Reverse faulting: black with white edges
- Strike-slip: cross pattern